

Ultrasound for Wireless Energy Transfer and Communication for Implanted Medical Devices

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Outline:

1. Introduction
2. Description of the System
3. In-Vitro Platform
4. Measurements
5. Conclusion

Outline:

1. Introduction

1.1 Aspects of Implanted Medical Devices

1.2 ULTRAsponder Goals

2. Description of the System

3. In-Vitro Platform

4. Measurements

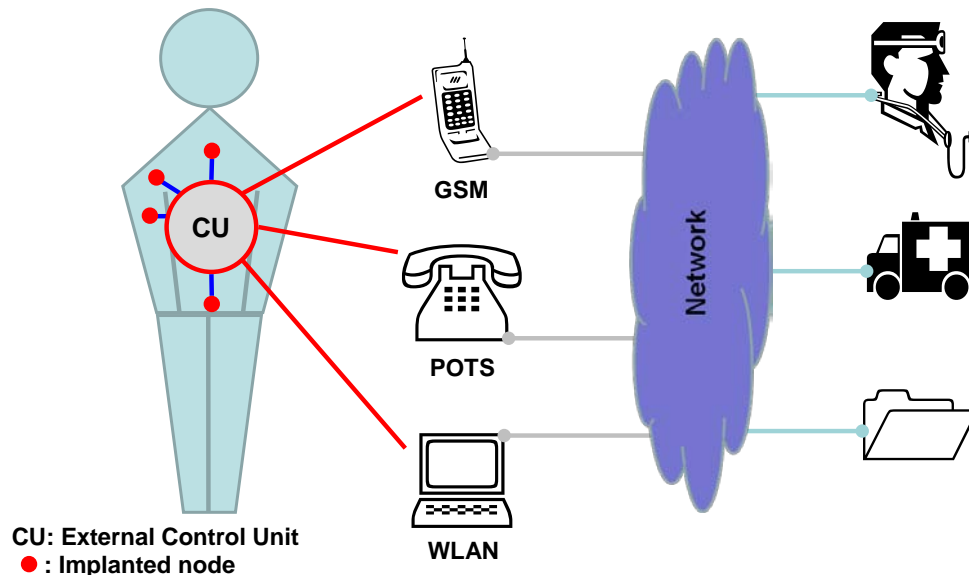
5. Conclusion

1.1 IMDs Aspects: What is an Implanted Medical Device?

- Health care solution.
- Partially/totally introduced, surgically/medically, into the human body.
- Remain in the body after the procedure for many years.
- Treat/monitor physiological condition, such as temperature, pressure, or fluid flow.
- Different kinds of IMDs: pacemakers, implantable cardiac defibrillator (ICD), drug delivery systems and neurostimulators.

1.2 ULTRAsponder Goals

- Continuous monitoring system to help patients lead a normal and healthy life.
- Wireless communication would help monitor patients during normal activity.



*source: www.ultrasponder.org

Outline:

1. Introduction
2. Description of the System
 - 2.1 Requirements
 - 2.2 Why Ultrasound?
 - 2.3 Rechargeable battery
 - 2.4 Modulator
3. In-Vitro Platform
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2.1 System Requirements

IMD deeply and totally introduced into the human body:

- Type of AC Source
- Implant Size
- Long Term Implant
- Long Autonomy
- Low-Power Circuitry (Modulator)

2.2 Why Ultrasound?

- To overcome electromagnetic attenuation limit in water:

ACOUSTIC
RF
MAGNETIC

Attenuation @ 10-20 cm

8-16 dB (@ 1 MHz)^[1]

60-90 dB (@ 2.45 GHz)^[2]

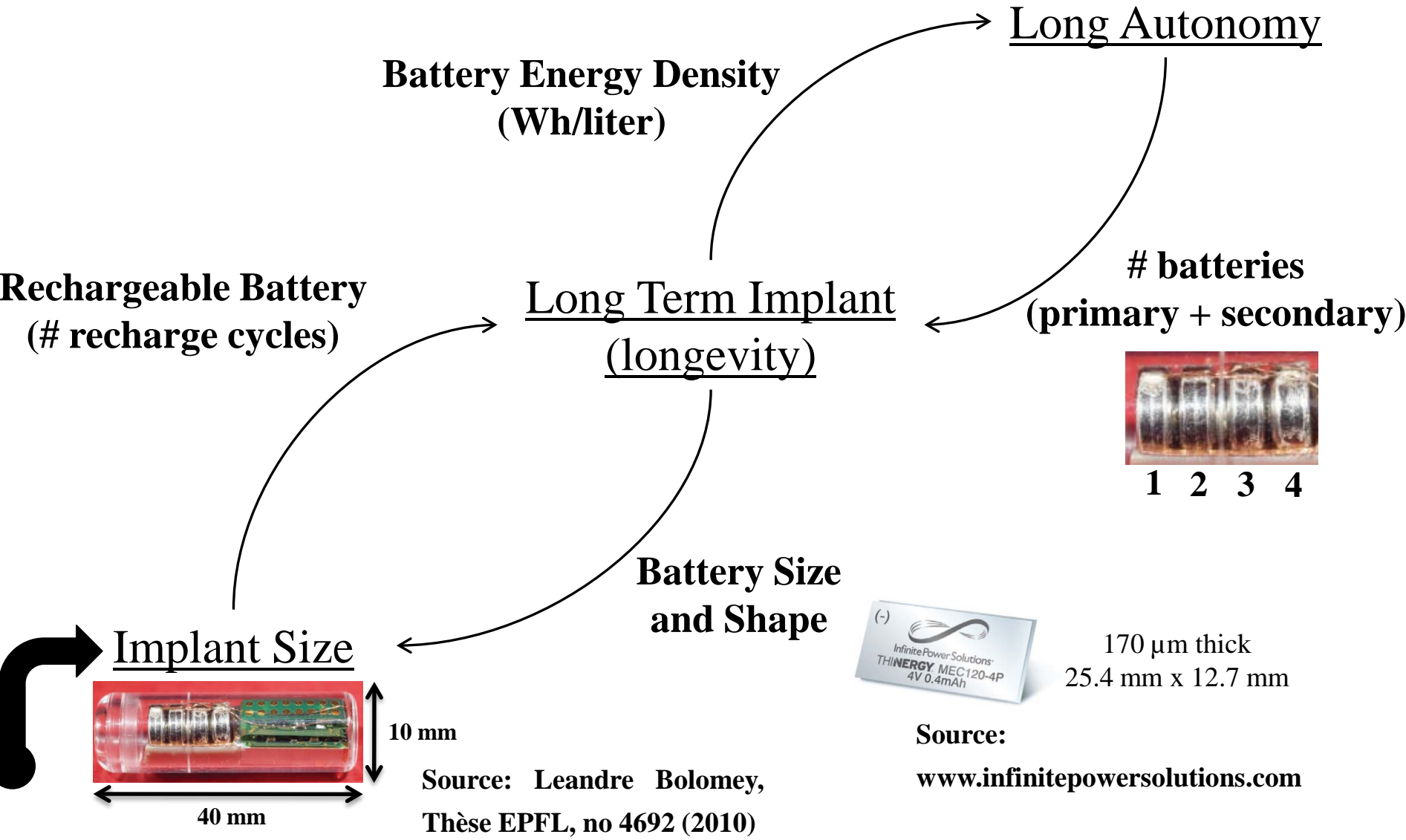
50 dB (@ 1 MHz)^[2]

- Inherently avoid interference with other medical systems (magnetic resonance imaging, pacemaker, ...).

[1] Francis A. Duck., *Physical Properties of Tissue*, 1990.

[2] Tomohiro Yamada et al., *JJAP*, 44(7A), 2005.

2.3 Rechargeable Battery



2.4 Modulation Technique

- Backscattering modulation also known as load or impedance modulation.
- Low power $\sim \mu\text{W}^{[3]}$.
- Concept is well-known in RF:
 - 1) A continuous or pulsed wave is transmitted from a control unit towards a transponder.
 - 2) The transponder reflects the wave back by changing its load impedance.
 - 3) The received echo at the control unit is demodulated.

[3] Giovanni de Vita et al., JM, 37(7), 2006.

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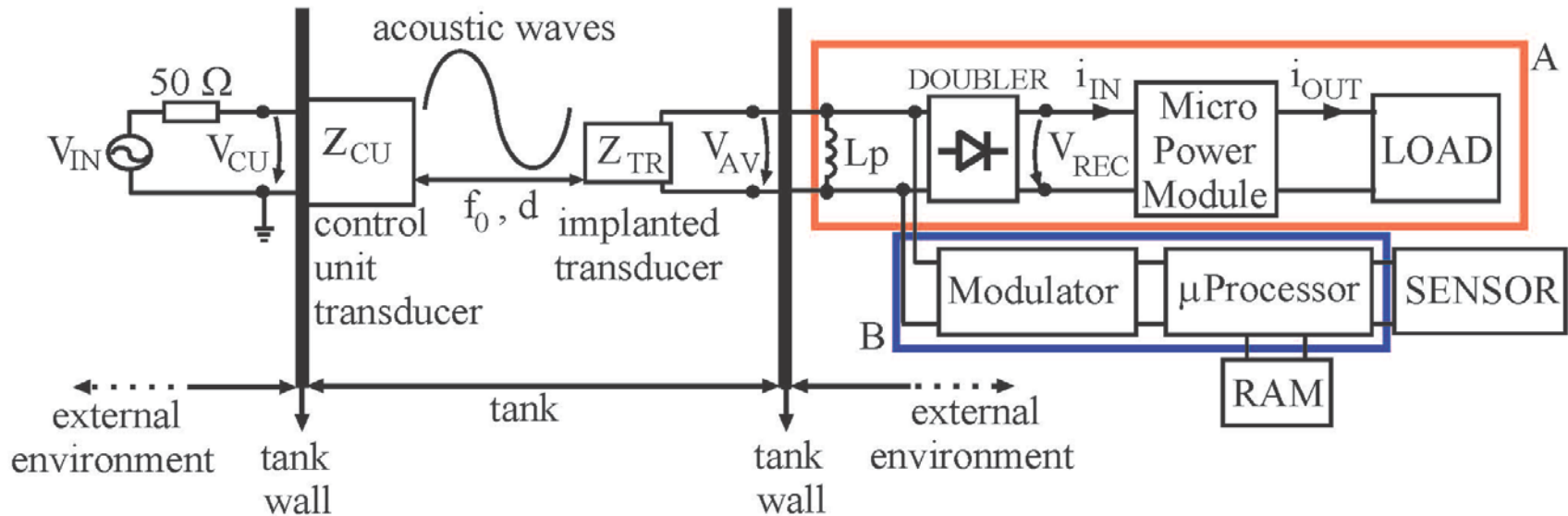
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 - 3.1 In-Vitro Before In-Vivo
 - 3.2 Overview
 - 3.3 Requirements
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3.1 In-Vitro Before In-Vivo

- Primary analysis of side effects.
- Helps in the various design stages of the IMD.
- User requirements (medical doctor, patient) and system specifications are defined.

3.2 Platform Overview^[4]

- Ultrasound energy harvesting (**module A**)
- Ultrasound wireless communication (**module B**)



[4] Francesco Mazzilli et al., EMBC, 2010

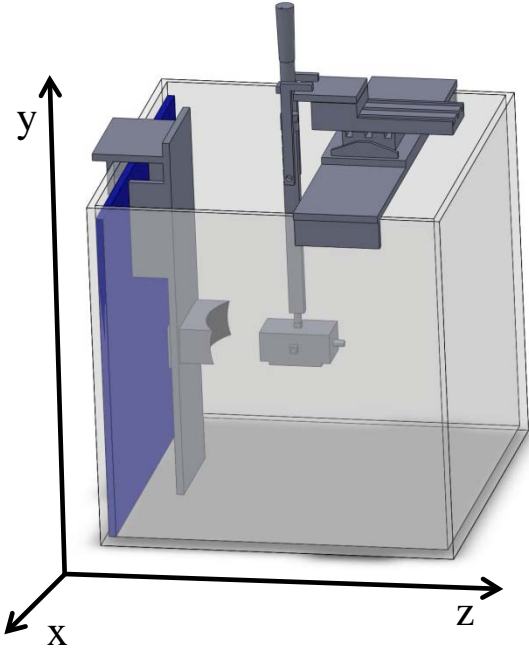
3.3 Platform Requirements

Anechoicity

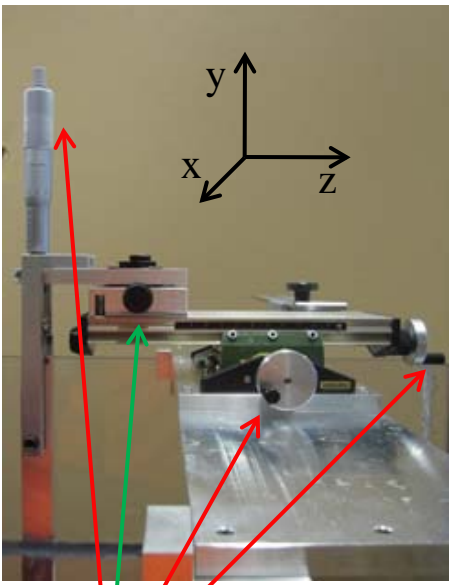


APTIFLEX 28^[5]

Dimension (125 liter)



Flexibility of motion



- x, y and z displacement
- x rotation

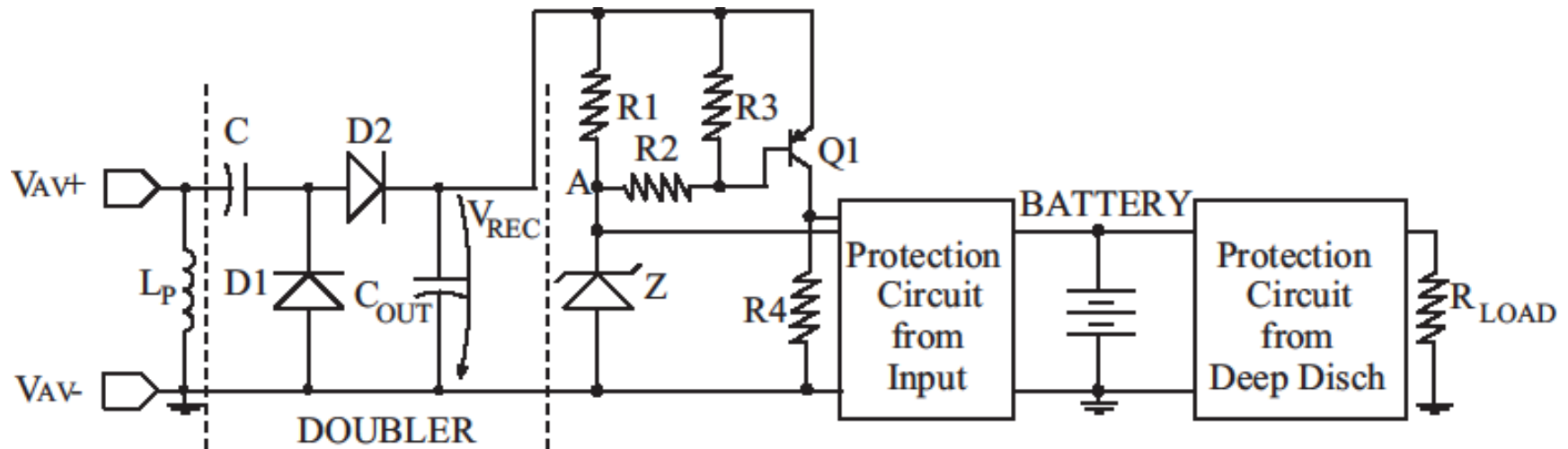
[5] <http://www.acoustics.co.uk/products/aptflex-28>

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4. Measurements
 - 4.1 Energy Harvesting
 - 4.2 Wireless Communication
5. Conclusion

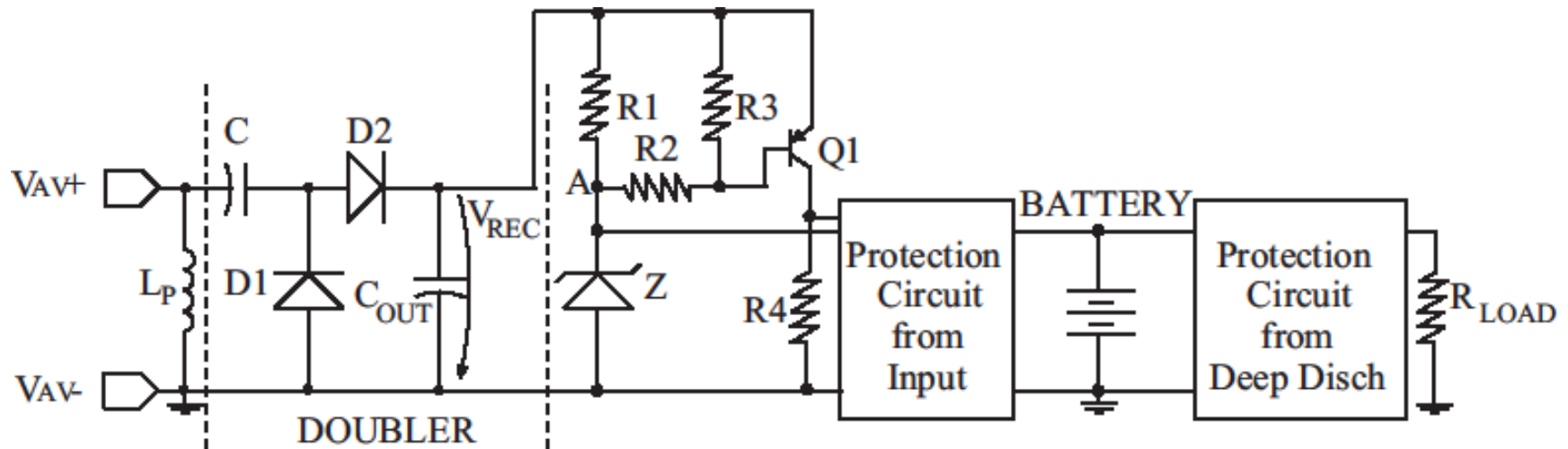
4.1 Energy Harvesting: Circuit (1/5)

- V_{AV} is the output signal yielded by the piston transducer (Pz26);
- V_{REC} is the output of the doubler;
- Voltage at node A is set to 4.1 V by the Zener diode;
- Two circuits to protect the battery against no input supply ($V_{AV} < 4.7$ V) and to avoid excessive discharge.



4.1 Energy Harvesting: Circuit (2/5)

- No matching network at the interface between the doubler and the transducer;
- L_p (ferrite coil) is used to tune out imaginary parts, both transducer and input recharging circuits at 1 MHz;
- Lithium Polymer Ion (LIPON) Battery \rightarrow Capacity 300 μ Ah (manufacturer Infinite Power Solutions).



4.1 Energy Harvesting: Transducers (3/5)



Single element focused transducer:

Central frequency = 1.1 MHz

Diameter = 50 mm

Focal distance = 50 mm

Thickness = 2 mm

Piezo material = Ferroperm Pz28 [6]

[6] Ferroperm Piezoceramics A/S



Single element piston transducer:

Central frequency 1.05 MHz

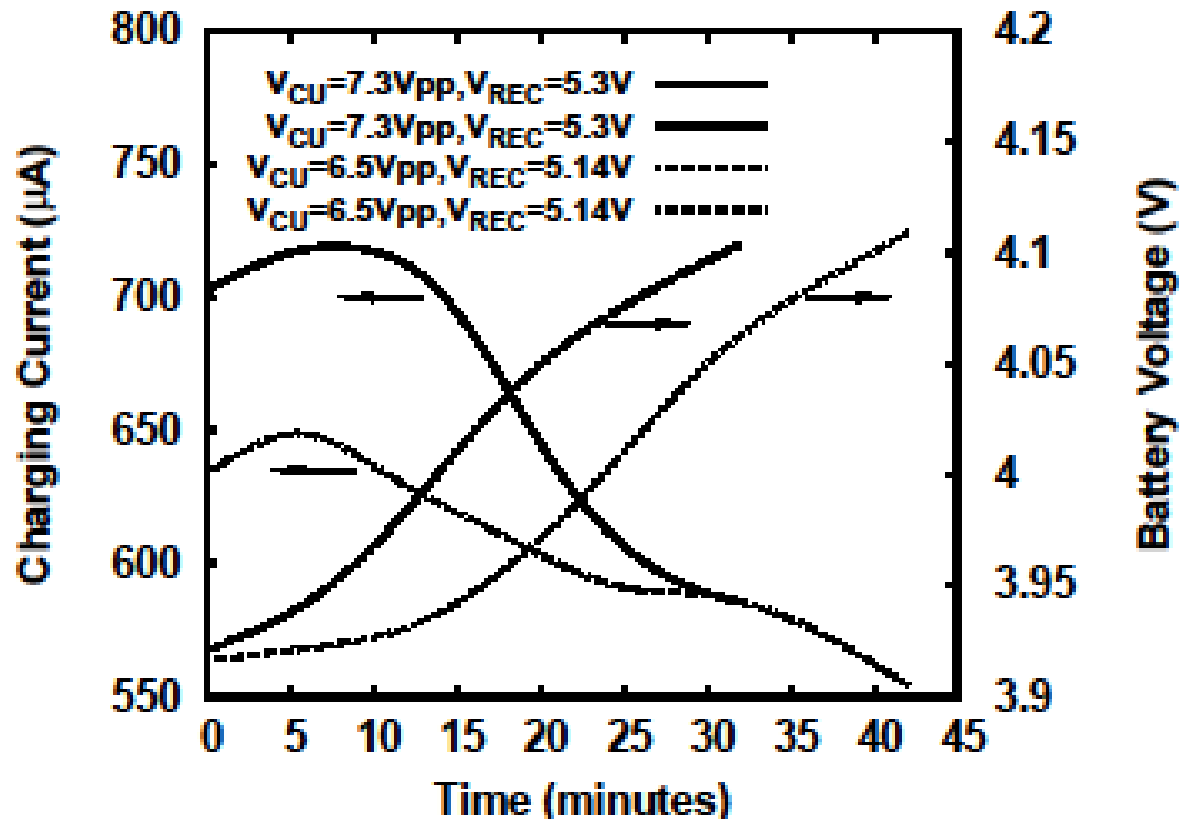
Diameter = 6.35 mm

Thickness = 2 mm

Piezo material = Ferroperm Pz26 [6]

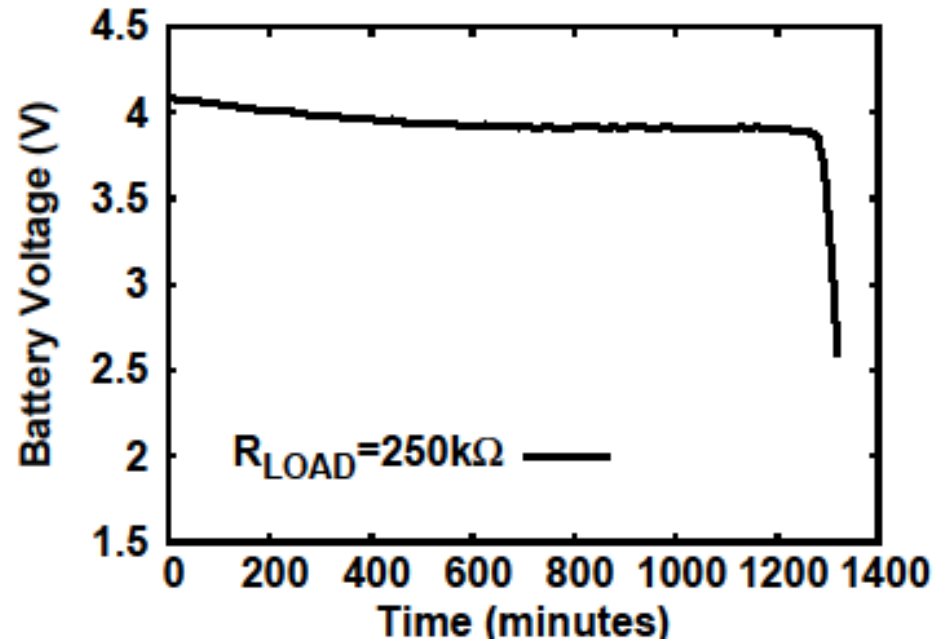
4.1 Energy Harvesting: Charge (4/5)

- Charging voltage 4.1 V.
- End of charge detected at 4.1 V battery voltage.



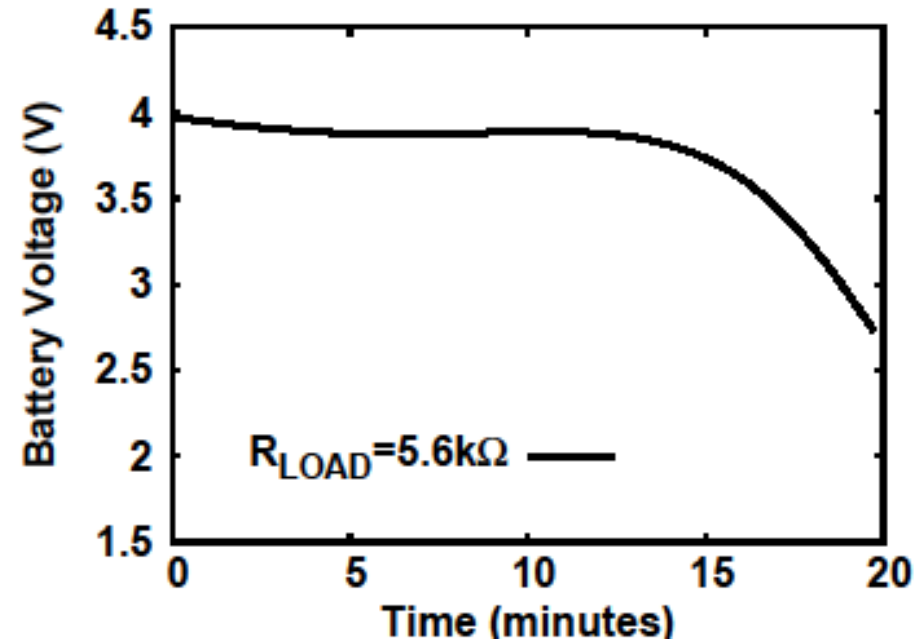
4.1 Energy Harvesting: Discharge (5/5)

- Discharging under **constant load**.
- Cut-off battery voltage at 2.5 V.



Discharge time ~ 22 hours

Discharge current ~ $16\mu A$



Discharge time ~ 20 minutes

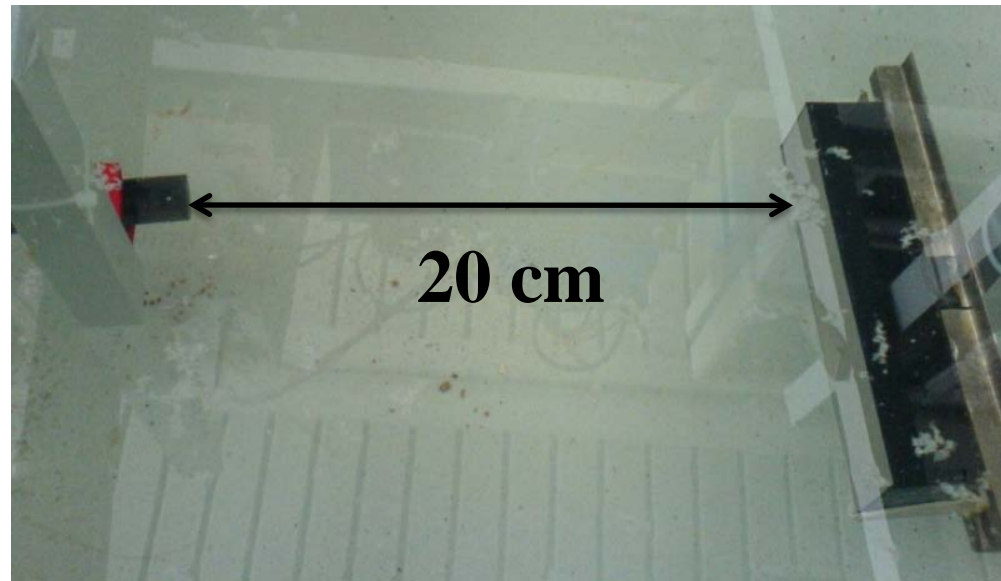
Discharge current ~ $730\mu A$

4.2 Wireless Communication: Specifications (1/4)

- Different pair of transducers.
- An array of elements is used for the control unit (READER), one element is used as transmitter and a second element is used as receiver.
- The transponder (TAG) modulates the incident wave (back-scattering modulation).
- On-Off Keying (OOK) modulation.
- Data rate 20 Kbps.
- The demodulator is present on the READER side, two amplifiers are used (gain of 20 dB per amplifier) to raise the amplitude of the received wave.

4.2 Wireless Communication: Transducers (2/4)

Linear phase array – 64 elements:
Central frequency = 1 MHz
Manufacturer IMASONIC



Single element piston transducer:

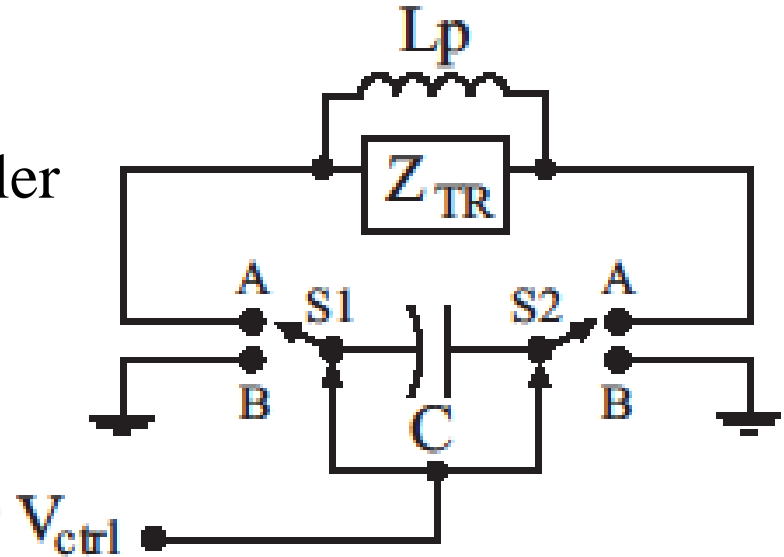
Central frequency = 1 MHz

Diameter = 13 mm

Manufacturer IMASONIC

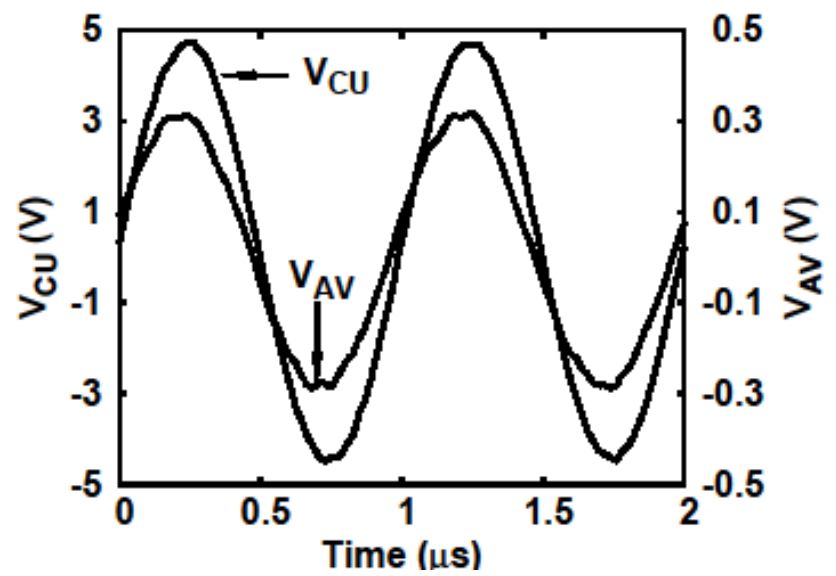
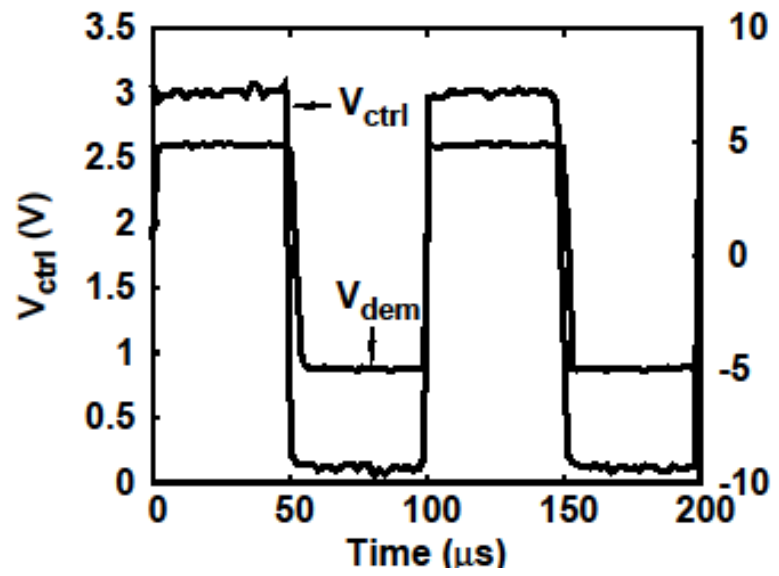
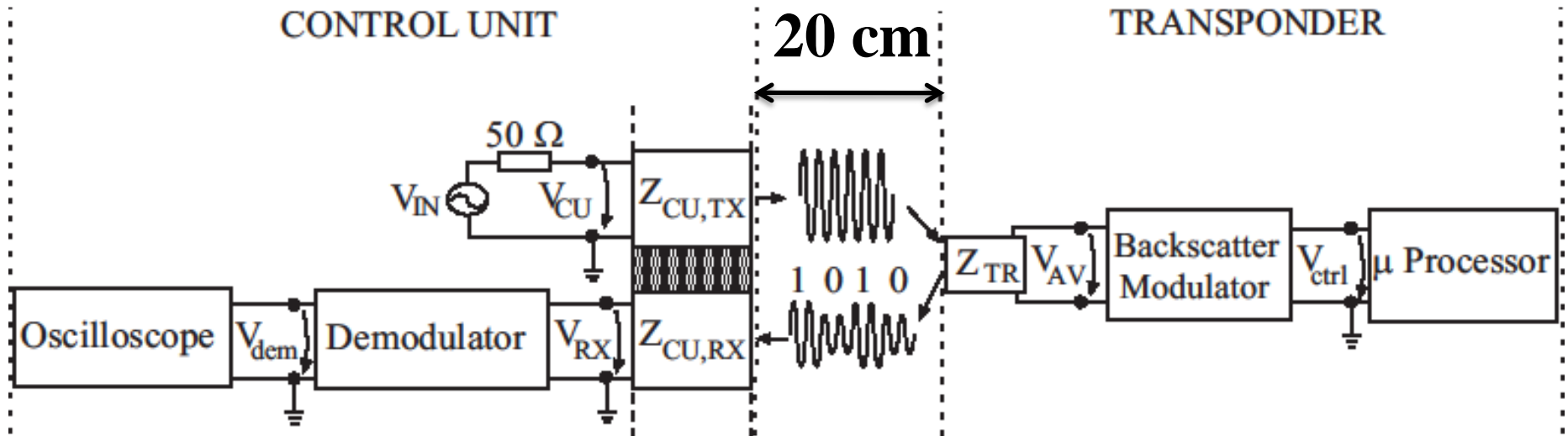
4.2 Wireless Communication: Modulator (3/4)

data signal yielded by a μ -controller that controls the switches.



- $V_{ctrl} = 1$, switch **S1 & S2 in position A**: The transducer is made stiffer and reflects back the incoming signal so a **high state is transmitted** to the CU receiver.
- $V_{ctrl} = 0$, switch **S1 & S2 in position B**: The transducer is allowed to vibrate so that the incoming signal is absorbed, thus a **low state is transmitted** to the CU receiver.

4.2 Wireless Communication: Results (4/4)



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- Platform for in-vitro testing of IMDs.
- Energy Harvesting via Ultrasound.
- Wireless Communication via Ultrasound.

Acknowledgement

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